# Walchand College of Engineering, Sangli

(Government Aided Autonomous Institute)

### AY 2024-25

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Prog	ramme
Class	, Semester
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B.Tech.

SY BTech Sem - IV Course Code

7MD221

Course Name

Introduction to Electric Vehicle

**Desired Requisites:** 

Nil

Teachi	ng Scheme		Examination	Scheme (Marks)		
Lecture	3Hrs/week	MSE	ISE	ESE	Total	
Tutorial	-	30	20	50	100	
	-	Credits: 3				

## **Course Objectives**

- Study the key components of EVs, such as batteries, electric motors, inverters, charging 1 systems, and energy management systems.
- Gain knowledge of the electric powertrain, including electric motors, controllers, and battery 2 management systems.
- Investigate the global market trends for EV adoption, including government incentives, market 3 barriers, and consumer behaviour

# Course Outcomes (CO) with Bloom's Taxonomy Level

At the end of the course, the students will be able to,

со	Course Outcome Statement/s	Bloom's Taxonomy Level	Bloom's Taxonomy Description
COI	Learn the basics of EVs, including their components, how they differ from internal combustion engine (ICE) vehicles, and their importance	II	Understand
CO2	Design and analyse the electric powertrain system of an EV, including electric motor selection, inverter design, and drivetrain integration.	IV	Analyse
CO3	Evaluate the performance characteristics of electric vehicles, including acceleration, braking, and overall efficiency, and relate these to vehicle design parameters.	V	Evaluate

Module	Module Contents	Hours
I	Background Details to Electric Vehicle (EV) EV Historical Background, EV Benefits of Using EVs, EV Overview of types of EVs and its Challenges, EV Motor Drive Technologies, EV Energy Source Technologies	6
II	Electric Vehicle Dynamics (Subsystems and Configuration) EV Subsystems and Modes of Operation. Vehicle Dynamics intro and tractive effort Configuration locomotive drives- series parallel switching-load tracking architecture. Mild hybrid- power assist- dual mode- power split- power split with shift, Continuously Variable transmission (CVT)-wheel motors.	6
Ш	Electrical & Electronic Components	7

	Purpose and operation of electrical components like switches, relays, solenoids etc. Purpose of circuit protection devices like fuses, circuit breakers and fusible links. Working of Electromagnetic gauges like temp Gauges, fuel gauge, engine oil pressure gauge, Speedo-meter gauge. Working of electrical accessories like windshield wiper, washer pumps, electrochromic mirror, power window, power seat, power door lock.	
IV	Clutches, Gear Box and Final Drive Principle, functions, general requirements, types of clutches Necessity of gear box, Requirements of gear box, Functions of gear box, Types of gears used in transmission, Gear shifting mechanism. Propeller shaft, universal joints, hooks and constant velocity joints, Drive line arrangements –Different types of final drives, need of differential.	7
V	Battery (Fuel Cells) Lead acid battery-components & operation. Maintenance free battery-construction. Concept of Low maintenance battery. Battery maintenance and safety precautions. Battery testing-Battery terminal test. Leakage test, Open circuit test, Capacity test. Battery charging-Initial charging procedure, dry charged battery precautions. Jump Starting-Procedure and precautions. Factors affecting battery life. Battery failures-cycle failure, internal short circuit, over charging.	6
VI	Brake, Steering and Suspension System Concept, function, working principle and necessity of brakes. Classification of brakes and braking systems. Electrical braking systems. Concept, function, working principle of Steering system. Electric power steering system (EPS) and its components. Concept, function, working principle and necessity of suspension system (ESS), electronic suspension system (ESS)	7
	Text Books	
1	Sandeep Dhameja "Electric Vehicle Technology" Macmillan India 2009	
2	G. S. S. Raiu & K. R. Padiyar "Electric Vehicles: The Way Forward" Wiley India	a 2017
3	D. K. Kothari & I. J. Nagrath "Electric Vehicle Engineering" McGraw-Hill Educa	ition 2019
	D. C.	
	References  1. 1. M. Mill. "Electric Vehicle Engineering" CRC Proce 2010	
<u>l</u>	John M. Miller "Electric Vehicle Engineering" CRC Press 2010  James L. W. Meintjes "Electric and Hybrid Vehicles: Design Fundamentals" CR	C Press 2012
2 3	Ali Emadi "Advanced Electric Drive Vehicles" CRC Press 2014	2 1 1 655 25 12
	S. K. Gupta "Hybrid Electric Vehicles: Principles, Design, and Applications"	PHI Learning
4	Private Limited 2012	
	Useful Links	
1	https://archive.nptel.ac.in/courses/108/106/108106170/	
2	https://nptel.ac.in/courses/108102121 https://www.shiksha.com/online-courses/fundamentals-of-electric-vehicles-techn	ology-
3	economics-course-nptel818	0.06)
	CO-PO Mapping	
And and continuous and the conti	Programme Outcomes (PO)	PSO
	1 2 3 4 5 6 7 8 9 10 11 12	1 2
CO1	3	
CO <sub>2</sub>	3 3 1	
CO3	2 2 3 2	
The stre	ngth of mapping is to be written as 1: Low, 2: Medium, 3: High	
Each CC	Of the course must map to at least one PO.	
Each CC	Assessment (for Theory Course)	

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The assessment is based on MSE, ISE and ESE. MSE shall be typically on modules 1 to 3.ISE shall be taken throughout the semester in the form of teacher's assessment. Mode of assessment can be field visit, assignments etc. and is expected to map at least one higher order PO.ESE shall be on all modules with around 40% weightage on modules 1 to 3 and 60% weightage on modules 4 to 6. For passing a theory course, Min. 40% marks in (MSE+ISE+ESE) are needed and Min. 40% marks in ESE are needed. (ESE shall be a separate head of passing)

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				Y 2024-25				
Ducas				e Information				
Progr		mester	MDM (Smart C B Tech, IV Sem					
Cours			7MD222	lester				
Cours			Introduction to U	Irban Planning				
		Requisites:	NIL	Oldan I familing				
Desir	cu i	Acquisites.	IVIL					
May 1	Tea	ching Scheme		Examination	n Scheme (N	Tarks)	(62.5)	
Lectu	-	3 Hrs/week	MSE	ISE	ESE	Tota	I	
Tutor	ial	-	30	20	50	100		
Practi	ical	-			L			
Intera	acti	on -	Credits: 3			***		
Cours		bjectives						
1		o understand the evol			nning.			
3		o analyse urbanizatio						
		o assess urban planni Outcomes (CO)	ng principles to add	dress contempora	ry challenges			
		of the course the stu	dents will be able t	to			11.49	
СО	Γ		Description			Blooms Taxon	omy	
	E	valain urbanization		ing anough and		Descriptor	Leve	
challenges.			in terms of planin	n terms of planning, growth and associated			2	
CO2	A	pply the concept of u						
CO3		nal yze the urban grov				Analyzing	3	
CO4	In	plement the GIS for	data collection and	l analysis for urba	n planning.	. Applying	4	
M - J								
Modu	iie		Mod	lule Contents			Hou	
		Evolution of town	nlanning				S	
				form, Concept	of urban hi	ıman settlement		
		Evolution in planning and physical form, Concept of urban human settlement, Differentiation between rural and urban settlement, concept of town, Evolved and						
I		Created Town Characteristics, Features of urban planning process, Role of urban						
		planner, Genesis of urban form; Social, Geographical and Cultural impacts, Contemporary developments in planning, Impacts of Industrial revolution on town and						
		regional planning, C	opments in plannif	ng, Impacts of Ind	ustrial revolu	ition on town and		
		Urbanization	naractoristics of se	ttroments.				
		Demography and (						
		Planning policies fr						
II		Rural and urban Mig					8	
		Master Plan; its of Perspective plan, Zo	eiements, preparat	tion and implen	nentation; P	erspective Plan,		
		Planning Acts, conce			piaillillg, I	own and Country		
	7	Urban Growth	F	-,				
		Elements of town s	ructure, Town cla	ssification: Funct	tional and ge	eographical; City		
		Centre, walled city	and Urban Fringe	e areas; classifica	ation based of	on socio-cultural	6	
Ш	1			The second secon				
III		characteristics, chan urban environment	ges with time and	growth, growth th	heories, Chai	acteristics of the	U	

IV	Urban Planning Principles and Policies Objectives and Principles of Urban planning, Environmental aspects of land use planning, concept of town planning scheme, Role of URDPFI guidelines in Town planning, demand and supply of land relationship, Government policies of urban development, Role of Professional bodies Concept of Neighbourhood Planning, Satellite Towns, Government Policies for small and medium towns, Urban and Rural Planning Rural-Urban Fringe.	7
V	Remote Sensing and GIS for Urban Planning Introduction to Remote Sensing and GIS for Urban Planning, Urban Land Use and Land Cover Analysis, GIS-Based Spatial Analysis for Urban Infrastructure, Remote Sensing for Disaster and Risk Management in Urban Areas, Sustainable Urban Development Using GIS Tools, Application of total station, drone, GPS, computer aided design in urban planning.	6
VI	Urban Legislation and Challenges Impacts of urbanisation, socio – economic impacts of growth of population, Social and Economic Environmental Administrator, Levels of Urbanisation, Indian scenario - Issues and Policies, Global scenario, Future trends of urbanization, Case Studies. Legislation as tools of plan implementation and development; Review of Planning legislation in India, complaint and redress mechanism.	8
Text Bo	oks	
1	K. C. Shivrama Krishnan, "Revisioning Indian Cities", Sage Publications.	
2 .	R. Ramachandran, "Urbanisation and Urban Systems in India", Oxford Publications.	
3	Urban and Regional Development Plan Formulations and implementation (URI guidelines, 2015.	OPFI)
Reference		
1	A.B. Gillion and Simon Eisner, "The Urban Pattern", CBS Publishers and Distributors,	Delhi.
2	Rishma A., "Town Planning in Hot Cities", Mir Publishers, Moscow	
3	Ward S (2002), "Planning the 20th Century City" John Wiler & Sons.	
4	Rangwala S.C" Town Planning"	
Useful L		
1	https://youtu.be/q_XmlG3CwNk?si=VP4rKCERXLKlgspV	
2	https://www.bo/DadoT2LLatLI2ai-vCLlply/fV0IV0V2V	-
3	https://youtu.be/RqdaT3LLctU?si=uSUnIy4fX8IX8K2K https://onlinecourses.nptel.ac.in/noc22 ar18/preview	

	Programme Outcomes (PO)									PSPO				
COs	1	2	3	4	5	6	7	8	9	10	11	12	1	2
CO1	3													
CO2			3											
CO3				2										
CO4				2										

## Assessment

- o The assessment is based on MSE, ISE, and ESE.
- o MSE shall be typically on modules 1 to 3.
- o ISE shall be taken throughout the semester in the form of a teacher's assessment. The mode of assessment can be field visits, assignments, etc., and is expected to map at least one higher-order PO.
- o ESE shall be on all modules with around 25-30% weightage on modules 1 to 3 and 70-75% weightage on modules 4 to 6.
- o For passing a theory course, Min. 40% marks in (MSE+ISE+ESE) are needed, and Min. 40% marks in ESE are needed. (ESE shall be a separate head of passing)



Prepared by	DAC/BoS Secretary	Head/BoS Chairman

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-		AY	2024-25	<b>1</b>	
	-	Course 1	Information		
Programme		B.Tech. (All Bra			
Class, Seme	ster	Second Year B.			
Course Cod	e	7MD223			
Course Nam		Introduction to I	Financial Markets		
Desired Req	uisites:	1	9		
Teach	ing Scheme		Examination Sc	cheme (Marks)	
Lecture	3 Hrs/week	ISE	MSE	ESE	Total
Tutorial		20	30	50	100
Practical					
Interaction	-		Credi	ts: 3	
		Course (	Objectives		
1	To provide four the economy.	idational knowledg	e of financial mark	ets, instruments, an	d their role in
2	To introduce ke derivatives, and		ents and asset class	es such as equity, d	lebt,
3		nderstanding of the at in capital markets	e principles of accors.	unting, investing, to	rading, and
			th Bloom's Taxon	omy Level	
At the end of t	the course, the stud	lents will be able to	),		
CO1			oning of financial r		Understand
CO2	Analyze the chadebt, and alterna		ncial instruments,	including equity,	Analyze
CO3	Apply the conc statements.	epts of accounting	g to prepare and in	nterpret financial	Apply
CO4	Evaluate investment fund performance	m.m.	and strategies, inclu	ding mutual	Evaluate

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Module	Module Contents				
I	Module 1: Basics of Accounting – Principles and Concepts Financial Accounting: Key accounting principles and concepts,	PARKET CAPA & CHIEF CAPA CAPA CAPA CAPA CAPA CAPA CAPA CAP			
	significance of accounting.	4			
	Accrual vs. cash accounting, double-entry bookkeeping.				
	Overview of the accounting cycle: Journal, ledger, trial balance.				
	Module 2: Financial Statements and Ratios	2			
$\mathbf{II}$	Understanding financial statements: Balance Sheet, Profit & Loss				
	Account, and Cash Flow Statement.	8			
	Financial ratios and their implications: Liquidity, profitability, and	٥			
	leverage ratios.	2			
	Practical exercises: Preparing basic financial statements.				
0.0000000000000000000000000000000000000	Module 3: Introduction to Financial Markets				
III	Overview of financial systems: Intermediaries, regulators, and				
	participants.				
	Functions of financial markets: Allocation of resources, risk	0			
	management, and price discovery.	9			
	Types of financial markets: Money Market vs. Capital Market;				
	Primary vs. Secondary Market.				
	Regulatory Framework in India: Role of SEBI and RBI.				
	Module 4: Capital Market Instruments – Equity				
IV	Equity instruments: Share and Stock Market operations - IPOs, FPOs,	0429			
	stock exchanges, indices, and trading mechanisms, Key factors	5			
	influencing equity prices, Risk-return trade-off in equity investments.				
	Module 5: Capital Market Instruments – Debt				
V	Debt instruments: Bonds, debentures, and fixed-income securities.	5			
	Bond valuation, yield, maturity, and duration.				
	Module 6: Mutual Funds and Alternative Investments				
VI	Overview of mutual funds: Structure, types, and advantages.				
	Net Asset Value (NAV) and fund performance metrics.				
	Introduction to alternative investments: Real estate, commodities,	8			
	private equity and hedge funds.				
	Fund Types: Active vs. Passive, ETFs, Index Funds				
	Text Books				
1	Indian Financial System by Bharati V. Pathak (Pearson).				
	Financial Accounting: A Managerial Perspective by R. Narayanaswamy (	PHI			
2	Learning).				

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	Reference Books
1	Investment Analysis and Portfolio Management by Prasanna Chandra for capital markets.
2	Mutual Funds in India: Structure, Performance, and Prospects by Amit Singhal (Springer).

### **Useful Links**

NSE India: https://www.nseindia.com - Official site of the National Stock Exchange of India.

BSE India: https://www.bseindia.com - Official site of the Bombay Stock Exchange.

**Investopedia**: <a href="https://www.investopedia.com">https://www.investopedia.com</a> - Comprehensive resource for financial concepts, markets, and instruments.

**SEBI**: <a href="https://www.sebi.gov.in">https://www.sebi.gov.in</a> - Securities and Exchange Board of India official site for regulations and updates.

RBI: <a href="https://www.rbi.org.in">https://www.rbi.org.in</a> - Reserve Bank of India official site for monetary policy and regulations. Khan Academy - Finance and Capital Markets: <a href="https://www.khanacademy.org">https://www.khanacademy.org</a> - Free tutorials on financial instruments, markets, and accounting.

**Morningstar**: <u>https://www.morningstar.in</u> - Resource for mutual fund analysis and performance tracking.

Zerodha Varsity: https://zerodha.com/varsity/ - Resource for Stock Market and Financial Education

						CO-	PO M	apping	;						
	Programme Outcomes (PO)														
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	
CO1	1				,										
CO2	1	2													
CO3	2				1				1						
CO4		1		1											

The strength of mapping is to be written as 1,2,3; Where, 1: Low, 2: Medium, 3: High Each CO of the course must map to at least one PO.

### **Assessment (for Theory Course)**

The assessment is based on MSE, ISE and ESE. MSE shall be typically on modules 1 to 3. ISE shall be taken throughout the semester in the form of teacher's assessment. Mode of assessment can be field visit, assignments etc. and is expected to map at least one higher order PO. ESE shall be on all modules with around 40% weightage on modules 1 to 3 and 60% weightage on modules 4 to 6. For passing a theory course, Min. 40% marks in (MSE+ISE+ESE) are needed and Min. 40% marks in ESE are needed. (ESE shall be a separate head of passing)

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		and the second s	Course	Information			***************************************
Progr	ramme		MDM in Geomat	ics Engineering			
	, Seme	ster		B. Tech 5.	em II		
	se Cod		7MD22		and the second s		
Cour	se Nam	le	Surveying and M	apping		The second secon	
Desir	ed Req	uisites:		hics, basic geomet	ry and geo	graphy	
	Teachi	ng Scheme		Examination	Scheme (N	(arke)	
Lectu		2 Hrs/week	MSE	ISE	ESE	Tota	ıl
Tutor		1 Hr/week	30	20	50	100	
Pract		1 TII/ WCCK	30		30	100	THE REAL PROPERTY AND ADDRESS OF THE PARTY AND
Intera			Credits: 3				
Intera	action		Credits. 5				
2 3 Cours	To le		methods and instructions of to the description			ing.  Blooms Taxon	nomy
CO						Descriptor	Leve
COI			different types or ystems and map pr		ales, and	Understanding	I
CO2	egic scoutings - Court Courters		eying techniques f			Applying	III
CO3			ial photogrammetry			Applying	III
CO4	Unde	rstand GPS function	oning and its use in	surveying and ma	pping	Understanding	III
N/ - J	1_		N/- J	ıle Contents			TT
Modu		• • •		ile Contents			Hours
I	O le	velling, reciproca	levels and their call levelling, and e, Total Station, a	precise levellin	g. Survey	ing instruments:	4
II	Tr ad an	justments, and plo d applications.	elling: Concepts otting. Triangulation	and application and trilateration			4
		oordinate systems ertesian and geogr	s aphical map projec	tions and their ty	pes: Confo	rmal, equal-area,	

A. A. Magdur

Systems and Map Projections

Introduction to Maps

standardization.

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IV

MDM Course Contents for R Tech Programme AV 2024 25

and equidistant. Map datum: Concepts of MSL (Mean Sea Level), Geoid, spheroid,

and WGS-84. Importance of map datum in GIS and engineering applications.

Types of maps: Topographical maps, cadastral maps, thematic maps, engineering

maps. Scales of maps: large scale, medium scale, small scale, and their applications. Plotting accuracy and precision in map-making. Map sheet numbering and

Definition and significance of maps in engineering projects.

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V	and accu slop	their in racy. I	nporta ntrodu ⁄sis an	nce in	photog o Digi	gramm tal Ele	etry. R vation	elief d Model	lisplace ls (DE	ement : M). Ap	and its	effects ions of	t, scale, on map DEM in creation	1
VI	Intro rece GPS rece	oductio ivers, t error iver, ar lication	n to ime sy s and	stems, Biase k error	GPS s pseudo s: GP , multi	o-range S eph path er	e measi emeris	iremer error nosphe	nts, GF s, Sel eric err	PS meas lective for, trop	sureme availa oosphe	ents. ability, ric error	of GPS satellite rs recision	4
Text Boo	oks			AND AND COMPANY OF PROPERTY OF THE PROPERTY OF										
1	Bind	lra S. P	., "A (	Course	in Hig	hway I	Engine	ering",	Dhan	pat Rai	Public	cations,	5 <sup>th</sup> Editio	on 2012.
2	Kang	g-tsung dition,	Chan	g, "Int	roduc	tion to	Geog	graphic	Infor	mation	n Syste	ems", T	ata Mc0	GrawHill
3				Sarah ems" , F							Introd	uction	to Geog	graphica
Reference	es		Ephone 1922	ing store										
1	Func	lament Yen T	als of o	Global pyright	Position 20	oning S 00 Joh	System n Wile	Receivy & Sc	vers: A	A Softw c.	are Ap	proach	James	
2											ing Vo	ol. 1, 2 &	દ 3.	
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Useful L			1		177	141						estación es estación (estacon estacon e		
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2	http:	s://npt	el.ac.ii	n/cours	ses/10	610523	19						and the second second second second	ALIGNA MARKONINO DONO
3														
CO-PO	Mappi	ng												
		ý	Y	y		nme C			y	·	7		PS	
COs	1	2	3	4	5	6	7	8	9	10	11	12	1	2
CO1	2		1		1		2	1	2		1	2	1	
CO2	1	2	3	1					1					1
CO3	1		2	2	1						1		1	

#### Assessment

- o The assessment is based on MSE, ISE, and ESE.
- o MSE shall be typically on modules 1 to 3.
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A.A. Magdum

MDM Course Contents for R Tech Drogramme AV 2024 25

### **Tutorial**

# **Tutorial 1: Principles of Land Surveying**

- a. Overview of survey levels and classifications
- b. Levelling methods: Differential, reciprocal, and precise levelling

# **Tutorial 2: Levelling Methods**

- a. Differential levelling: Procedure and accuracy
- b. Reciprocal levelling: Elimination of errors

## Tutorial 3: Levelling Methods Applications of Surveying in Infrastructure Development

- a. Road alignment and construction
- b. Bridge and dam site selection

# **Tutorial 4: Advanced Surveying Techniques**

- a. Trigonometric levelling: Concepts and field applications
- b. Traversing: Methods, plotting, and adjustments

## **Tutorial 5: Systems and Map Projections**

- a. Introduction to map projection systems
- b. Importance of map datum in GIS and engineering

## **Tutorial 6: Introduction to Maps**

- a. Definition and significance of maps in engineering projects
- b. Types of maps: Topographical, cadastral, thematic, engineering maps

# **Tutorial 7: Aerial Photogrammetry**

- a. Types of aerial photographs: Vertical, oblique, panoramic
- b. Flying height, scale, and importance in photogrammetry

## **Tutorial 8: Global Positioning Systems (GPS)**

- a. GPS signal structure and modernization
- b. Types of GPS receivers and their applications

## **Tutorial 9: Global Positioning Systems (GPS)**

- a. GPS errors and biases: Ephemeris, selective availability, multipath, ionospheric, tropospheric
- b. Applications of GPS in utilities, forestry, and precision farming

## **Tutorial 10: Revision**

Prepared by	DAC/BoS Secretary	Head/BoS Chairman
Mr. A. A. Magdum	Dr. S. S. Karvekar	Dr. B. F. Momin

		Wal		e of Engineeri		i	
				Z 2024-25		**************************************	
	N. C.		Cours	e Information			
Progr	ramn	ne	B.Tech. (Artifici	al Intelligence and	Machine Le	earning)	
		nester	Second Year B.				
Cour		**************************************	7MD225				
Cour			<del></del>	ificial Intelligence a	and Machine	Learning	
		equisites:		ation, Linear Algeb			ili+v
Desir	- I	equisites.	basic of Optimiza	ation, Linear Algeb	ia, statistics	and Probab	ility
	Teac	ching Scheme		Examination	Scheme (M	(arks)	
Lectu	re	3 Hrs/week	ISE	MSE	ESF		Total
Tutor	ial	-	20	30	50		100
				Cr	edits: 3		
			<b>V</b>				
			Cours	se Objectives			
1	То	introduce concepts of	AIML				
2		align real world probl			ies		
3		explain AIML algorith		·····			
4	To	motivate students to g	A STATE OF THE PARTY OF THE PAR				
				with Bloom's Tax	onomy Leve	el	
CO	end	of the course, the stude	rse Outcome Stat			Bloom's Taxono my Level	Bloom's Taxonomy Description
CO1	Sun	nmarized AIML strate	gies and related te	erms		II	Understand
CO2		oose relevant domain a			ing	III	Apply
CO3		npare AIML algorith			nts.	IV	Analyse
CO4	Rec	ommend suitable sear	ch techniques in A	AIML algorithms		V	Evaluate
Modu	le		Module	Contents			Hours
Ι		Introduction to AI: History of Artificial In Applications of AIM Brief on: robotic v scheduling, game pla translation, LLM's, ga	ntelligence, Turing L: rehicles, speech s ying, spam filtering	test, cognitive mo recognition, autor ng, logistics plann	nomous plan	nning and	6
II		Intelligent Agents: Agents and environmentature of agents, applications.	ents, concept of rat	tionality, nature of			6



III	Solving Problems by Searching:  Search in artificial intelligence. problem solving with search. real-world applications of search (e.g., pathfinding, games). problem representation: representing problems as state spaces. defining states, actions, and goals. brief on: uninformed search strategies, informed (heuristic) search strategies. Beyond classical search: adversarial search, constraint satisfaction problems.	7
IV	Knowledge and Reasoning:  Logical agents, knowledge-based agents, propositional logic, propositional theorem proving, agents based on propositional logic.	6
V	First-Order Logic: Syntax and semantics of first-order logic, using first-order logic, knowledge engineering in first-order logic,inference in first-order logic,propositional vs. first-order inference, unification and lifting forward chaining, backward chaining,resolution.	7
VI	Foundation of Machine Learning: Supervised learning: regression and classification problems, simple linear regression, multiple linear regression, logistic regression.	7
	Textbooks	
1	Stuart J. Russell and Peter Norvig, "Artificial Intelligence: A Modern Approach", edition, 2022.	
2	Deepak Khemani," A First Course in Artificial Intelligence", McGraw Hill Education (	India 2012
3	j = copenitional, it is not consider in the second of the constitution (	iliula), 2013.
	Géron, Aurélien,"Hands-On Machine Learning with Scikit-Learn, Keras, and O'Reilly Media, 2nd edition, 2019.	
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	Géron, Aurélien,"Hands-On Machine Learning with Scikit-Learn, Keras, and O'Reilly Media, 2nd edition, 2019.  References	TensorFlow",
1	Géron, Aurélien,"Hands-On Machine Learning with Scikit-Learn, Keras, and O'Reilly Media, 2nd edition, 2019.	TensorFlow",  Saddle River, e personalized
1 2	Géron, Aurélien,"Hands-On Machine Learning with Scikit-Learn, Keras, and O'Reilly Media, 2nd edition, 2019.  References  Norvig, P. R., & Intelligence, S. A. (2002). A modern approach. Prentice Hall Upper NJ, USA: Rani, M., Nayak, R., & Vyas, OP (2015). An ontology-based adaptive e-learning system, assisted by software agents on cloud storage. Knowledge-Ba	TensorFlow",  Saddle River, e personalized ased Systems,
	Géron, Aurélien,"Hands-On Machine Learning with Scikit-Learn, Keras, and O'Reilly Media, 2nd edition, 2019.  References  Norvig, P. R., & Intelligence, S. A. (2002). A modern approach. Prentice Hall Upper NJ, USA: Rani, M., Nayak, R., & Vyas, OP (2015). An ontology-based adaptive e-learning system, assisted by software agents on cloud storage. Knowledge-Ba 90, 33-48.  Stefan Edelkamp and Stefan Schroedl,"Heuristic Search: Theory and Application	TensorFlow",  Saddle River, e personalized ased Systems,
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2	Géron, Aurélien,"Hands-On Machine Learning with Scikit-Learn, Keras, and O'Reilly Media, 2nd edition, 2019.  References  Norvig, P. R., & Intelligence, S. A. (2002). A modern approach. Prentice Hall Upper NJ, USA: Rani, M., Nayak, R., & Vyas, OP (2015). An ontology-based adaptive e-learning system, assisted by software agents on cloud storage. Knowledge-Ba 90, 33-48.  Stefan Edelkamp and Stefan Schroedl,"Heuristic Search: Theory and Application Kaufmann, 2011.  Useful Links	TensorFlow",  Saddle River, e personalized used Systems,

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The strength of mapping is to be written as 1: Low, 2: Medium, 3: High Each CO of the course must map to at least one PO.



## Assessment

The assessment is based on MSE, ISE and ESE.

MSE shall be typically on modules 1 to 3.

ISE shall be taken throughout the semester in the form of teacher's assessment. Mode of assessment can be field visit, assignments etc. and is expected to map at least one higher order PO.

ESE shall be on all modules with around 40% weightage on modules 1 to 3 and 60% weightage on modules 4 to 6.

For passing a theory course, Min. 40% marks in (MSE+ISE+ESE) are needed and Min. 40% marks in ESE are needed. (ESE shall be a separate head of passing)



#### Walchand College of Engineering, Sangli (Government Aided Autonomous Institute) AY 2024-25 **Course Information** Programme MDM: Robotics and Automation Class, Semester S. Y. B. Tech. - Sem IV Course Code 7MD226 Course Name Robotics Fundamentals and Design **Desired Requisites: Physics Teaching Scheme Examination Scheme (Marks)** Lecture 3 Hrs/week **MSE** ESE Total **Tutorial** 30 20 50 100 Credits: 3 **Course Objectives** To understand the fundamentals of robotics 1 2 To learn the working of- sensors, end effectors, drives To learn the selection of sensor, drives 3 4 To learn basics of end effector design and robot kinematics Course Outcomes (CO) with Bloom's Taxonomy Level At the end of the course, the students will be able to Bloom's Bloom's Taxonom CO Course Outcome Statement/s **Taxonomy** Level Descripti on CO<sub>1</sub> Recall fundamentals of robot anatomy, sensors, end effectors, drives, Remembe I power transmission and Kinematics ring CO<sub>2</sub> Explain the components, working of; robot components, sensors end Understan II effectors, transmission, drives and kinematics ding CO<sub>3</sub> Select appropriate sensor, end effector, drive and transmission Applying III elements CO<sub>4</sub> Analyze the design considerations of end effectors, power Analyzing IV transmission and kinematics Module **Module Contents** Hours **Fundamentals of Robotics** Historical development of Robotics, Definitions of Industrial Robot, Types and Classification of Robots, Asimov's laws of robotics, Robot I 6 configurations, Robot Components, Robot Degrees of Freedom, Work volume and work envelope, Robot Joints and symbols, Resolution, accuracy and precision of robot Sensors in robotics Sensor characteristics, Position sensors, Encoders, Resolvers, Velocity II sensors, Proximity sensors, Limit switches, Tactile sensors, Force and 6 torque sensors, Safety Sensor: Light Curtain, Laser Area Scanner, Safety Switches, Introduction to machine vision.

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III	End Effectors Grippers, Mechanical Grippers, Pneumatic and Hydraulic- Grippers, Magnetic Grippers, Vacuum Grippers; Two Fingered and Three Fingered Grippers; Internal Grippers and External Grippers; Advance Grippers- Adaptive grippers, Soft Robotics Grippers, Tactile Sensor Grippers; Various process tools as end effectors; Robot end effectors interface, Active and passive compliance, Selection and Design Considerations	7
IV	Robot drives Robot drive system, Types - Pneumatic, Hydraulic, Mechanical, Electrical Drives, Salient Features, Applications and Comparison of all these Drives, Micro actuators, selection of drive. Position and velocity feedback devices.	6
V	Power transmission Mechanical transmission method ,Gear transmission, Belt drives, cables, Roller chains, Link, Rod systems,Rotary-to-Rotary motion conversion, Rotary-to-Linear motion conversion, Rack and Pinion drives, Lead screws, Ball screws.	7
VI	Kinematics Kinematics - Definition, Importance in robotics, Mechanisms — Terminology, Kinematic chains, inversions, Forward kinematics, inverse kinematics, Basics of matrices, Rotations & transformations, Introduction to D-H parameters and its physical significance, Orientation of gripper, Trajectory planning, Motion interpolation, Control of robot manipulators — Point to point, Continuous Path Control	7
	Textbooks	
1	Groover, Mikell P. Industrial Robotics: Technology, Programming, and App 2nd ed., Special Indian ed, McGraw-Hill, 1986. ISBN: 9781259006210	lications.
2	Saha, Subir Kumar. Introduction to Robotics. Second edition, McGraw Hill E (India) Private Limited, 2014. ISBN: 9789332902800	Education
3	Craig, John J, "Introduction to Robotics: Mechanics and Control", Four Pearson, 2018., ISBN: 9780133489798	th edition
4	Jain, Anil K., "Fundamentals of Digital Image Processing", Prentice Hall, 198 9780133361650	89. ISBN
5	Poole, Harry H., "Fundamentals of Robotics Engineering", Springer Netherla 2012, ISBN: 9789401170505	nds,
	References  Niku Saced B. Introduction to Polytics: Analysis Control Applications 2n	d ad
1	Niku, Saeed B. Introduction to Robotics: Analysis, Control, Applications. 2n Wiley, 2011. ISBN-13: 978-9332902800	u eu,
2	Khatib, Oussama, and Bruno Siciliano, "Springer Handbook of Robotics", 2n Springer International Publishing: Imprint: Springer, 2016, ISBN: 978331932	
3	P.I. Corke, "Robotics, Vision & Control", Second edition, Springer, 2017, ISE 319-54413-7	
4	Ghosal, Ashitava. Robotics: Fundamental Concepts and Analysis. Oxford UPress, 2006. ISBN: 9780195673913	Jniversity
5	Mittal, R. K., and I. J. Nagrath. Robotics and Control. Tata McGraw-Hill, 200 13: 978-9332902800	)3. ISBN
	Useful Links	
1	https://www.automate.org/companies/robotic-industries-association	

2	https://www.ieee-ras.org/
3	https://www.roboticstomorrow.com/
4	https://www.designworldonline.com/
5	https://www.therobotreport.com/
6	https://robohub.org/
7	https://www.sciencedaily.com/news/computers_math/robotics/
8	https://techxplore.com/robotics-news/
9	https://nptel.ac.in/courses/107106090
10	https://nptel.ac.in/courses/112105249
11	https://onlinecourses.nptel.ac.in/noc21_me32/preview
12	https://archive.nptel.ac.in/courses/112/101/112101099/
13	https://archive.nptel.ac.in/courses/112/107/112107289/

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